Searching for Keywords
Search for keywords such as “battery” and “install” to find a topic. If you are using Adobe Acrobat Reader to read this document, press Ctrl+F on Windows or Command+F on Mac to begin a search.

Navigating to a Topic
View a complete list of topics in the table of contents. Click on a topic to navigate to that section.

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## Contents

<table>
<thead>
<tr>
<th>Title</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Disclaimer and Warning</td>
<td>2</td>
</tr>
<tr>
<td>Introduction</td>
<td>2</td>
</tr>
<tr>
<td>In the Box</td>
<td>2</td>
</tr>
<tr>
<td>Overview</td>
<td>3</td>
</tr>
<tr>
<td>Payload SDK Port</td>
<td>3</td>
</tr>
<tr>
<td>Payload Design Instructions</td>
<td>4</td>
</tr>
<tr>
<td>Payload Requirements</td>
<td>4</td>
</tr>
<tr>
<td>Payload Mounting Requirements</td>
<td>5</td>
</tr>
<tr>
<td>Mounting</td>
<td>6</td>
</tr>
<tr>
<td>Mounting the Payload to the X-Port Gimbal</td>
<td>6</td>
</tr>
<tr>
<td>Mounting the X-Port Gimbal to the Aircraft</td>
<td>8</td>
</tr>
<tr>
<td>Settings</td>
<td>8</td>
</tr>
<tr>
<td>The DA2 Page</td>
<td>8</td>
</tr>
<tr>
<td>The DJI Pilot App Page</td>
<td>9</td>
</tr>
<tr>
<td>Control Parameter Settings</td>
<td>11</td>
</tr>
<tr>
<td>User Parameter Settings</td>
<td>12</td>
</tr>
<tr>
<td>Other Parameter Settings</td>
<td>13</td>
</tr>
<tr>
<td>Functions</td>
<td>13</td>
</tr>
<tr>
<td>Gimbal Function Debugging</td>
<td>13</td>
</tr>
<tr>
<td>Gimbal Control</td>
<td>14</td>
</tr>
<tr>
<td>Appendix</td>
<td>14</td>
</tr>
<tr>
<td>Specifications</td>
<td>14</td>
</tr>
<tr>
<td>Firmware and Software Version Requirements</td>
<td>15</td>
</tr>
<tr>
<td>Firmware Update</td>
<td>15</td>
</tr>
<tr>
<td>Log Export</td>
<td>16</td>
</tr>
<tr>
<td>Mounting the Extended Landing Gears</td>
<td>16</td>
</tr>
<tr>
<td>Using the Special Gimbal Dampers</td>
<td>16</td>
</tr>
<tr>
<td>Obstruction in Dual Gimbal Installation</td>
<td>16</td>
</tr>
</tbody>
</table>
Disclaimer and Warning
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This disclaimer is available in various languages. In the event of divergence among different versions, the English version shall prevail.

Introduction
DJI ENTERPRISE X-Port (hereinafter referred to as “X-Port”) gimbal is designed to enable developers and manufacturers to create third-party payloads based on DJI’s gimbal technology, with access to its resources including power systems, communication links, and aircraft status parameters such as GPS data, flight attitude data, and app date and time. DJI also provides a suite of software products to support developers in using the X-Port gimbal, such as the Onboard SDK, Mobile SDK, the DJI Pilot app, and the DJI ASSISTANT™ 2 desktop application.

In the Box

<table>
<thead>
<tr>
<th>DJI ENTERPRISE X-Port Gimbal</th>
<th>Protection Cover</th>
<th>Primary Arm Mounting Screw</th>
</tr>
</thead>
<tbody>
<tr>
<td>×1</td>
<td>×1</td>
<td>×5</td>
</tr>
</tbody>
</table>
Overview

1. Yaw Base Centerline
2. DJI Gimbal Connector 2.0 (DGC2.0)
3. Yaw Motor
4. Yaw Base
5. Yaw Waterproof Sticker
6. Yaw Arm
7. Roll Motor
8. Roll Waterproof Sticker
9. Roll Arm
10. Pitch Axis Centerline
11. Pitch Secondary Arm Mounting Hole
12. Pitch Secondary Arm End
13. Pitch Primary Arm Mounting Hole
14. Pitch Primary Arm Waterproof Washer
15. Pitch Motor
16. Payload SDK Port
17. Pitch Primary Arm End
18. microSD Card Slot

Payload SDK Port

The X-Port gimbal connects the load via the Payload SDK (PSDK) port for both power supply and communication. See below for detailed pin descriptions.
### Number | Pin Name | Pin Type | Specification | Description
--- | --- | --- | --- | ---
1, 3, 5 | VCC | Power supply | 13.6 V / 2 A, 17 V / 2.5 A | Supply power for the PSDK load.*
2, 4, 6, 15 | GND |  |
7 | UART1_TX |  |
8 | UART1_RX |  |
9 | CAM_RDY |  |
10 | DRONE_TRIG | Reserved |  |
11 | USART2_TX | Reserved | UART TTL (3.3 V) | Communicates with the PSDK load.
12 | USART2_RX |  |
13 | VSYNC |  |
14 | PPS | Reserved | 0–3.3 V digital signal | The PPS signal generated from the aircraft, used for time synchronization.
16 | HIGH_POWER_APPLY | PPS signal | 0–3.3 V digital signal | The default aircraft output voltage is 13.6 V, which becomes 17 V once a high-power application has been raised.
17 | LAN_TXP | High-power application pin | 100 Mbps | Used for high-speed communication between the aircraft and the PSDK load.
18 | LAN_RXP |  |
19 | LAN_TXN |  |
20 | LAN_RXN |  |

* When used with the aircraft, the MATRICE™ 200 series V2 aircraft’s gimbal connector will supply the power of 4 A rated current (peak current <5). The DJI X-Port gimbal’s 3-axis stalled power consumption before take-off, and the hovering power consumption with 250 g load (indoor windless, and no remote controller operation) are as below:

<table>
<thead>
<tr>
<th>Gimbal power consumption</th>
<th>3-axis stalled power consumption</th>
<th>Hovering power consumption with 250 g load</th>
</tr>
</thead>
<tbody>
<tr>
<td>Normal Status</td>
<td>3.2 A / 13.6 V</td>
<td>1 A / 13.6 V</td>
</tr>
<tr>
<td>High-power Status</td>
<td>2.56 A / 17 V</td>
<td>0.8 A / 17 V</td>
</tr>
</tbody>
</table>

The gimbal connector voltage will decrease if the gimbal and load power consumption increase due to line loss. The gimbal consumption is related to load size, load shape, load inertia, load rotation speed controlled by gimbal, and upwind speed during flight. It is very important to ensure that the power provided to the load meets the load’s voltage and current requirements, as the gimbal actual power consumption may exceed the 3-axis stalled power consumption due to heavy load, larger upwind speed or quick load rotation speed during flight.

### Payload Design Instructions

Please follow the requirements below to design your payload when used with the X-Port gimbal.

#### Payload Requirements

1. **Mass**
   The total mass of the payload should not exceed 450 g.

2. **Shape**
   a. The dimension of the payload in the direction of the Pitch axis centerline is 80 mm. Note that this measurement must be accurate within the range of ± 0.1 mm. Otherwise, it may result in improper assembly or excessive frictional resistance, which will affect control.
b. Draw a spherical surface with a diameter of 136 mm, using the mass center of the load as the center of the sphere. Ensure that all movement of a load positioned to the back of the pitch axis centerline can be completely contained within this sphere.

- When used with the M200 Series V2, the extended landing gears are required to meet the diameter design specification of 136 mm. If using the default landing gears, it is required to limit the Pitch rotation or the spherical surface diameter must be 100 mm, otherwise, the payload may touch the ground when rotating.

c. Ensure that a load positioned to the front of the pitch axis centerline will not be blocked by the yaw arm when the load tilts up to 45°. If the front half of the load protrudes too far out, it might get in the way of other components during gimbal self-testing when using dual gimbals (the specific constraints of the front half part will vary depending on the type or size of the other gimbal in place), and the payload might touch the ground when the gimbal pitch rotates.

3. Stiffness

Ensure that there is enough connection stiffness between various payload components. It is recommended to use an aluminum alloy shell, avoiding 3D-printed or carbon fiber shells.

4. Waterproofness

Ensure the payload mounting interface

Payload Mounting Requirements

Please follow the descriptions below to design an adaptable installation interface for the payload based on the X-Port gimbal.

1. Primary Arm Mounting

Four primary arm mounting screws (M2) are needed to mount the payload. Their size requirements are shown in the figure. Ensure that the depth of the corresponding threaded hole in the payload is at least 5.3 mm.
2. Secondary Arm Mounting
   A secondary arm mounting screw (M3), an arm sleeve, and an arm plug are needed. Ensure that the secondary arm mounting screw goes through the pitch axis centerline.

3. Mass Center Position Requirement
   a. For a payload with a constant mass center, ensure that the mass center is on the pitch axis centerline.
   b. For a zoom camera with a variable mass center position, ensure that the mass center is on the pitch axis centerline when the lens is at maximum magnification.

Mounting

Mounting the Payload to the X-Port Gimbal

Payload Interface Mounting

The connector used to connect the gimbal and payload is a 20-pin board-to-wire connector from ACES Electronics Co., Ltd. The model is S-50420-020HKH0-001.

- Make sure to reserve a hole on the position where the payload is mounted on the gimbal pitch primary arm so that the connector end and the cable (the length is about 100 mm) can come out.
- DO NOT plug in or unplug the payload from the connector when powered on.

Payload Mounting Steps

Follow below steps to mount the payload to the gimbal.

1. Insert the 20-pin connector’s male end to the gimbal mainboard’s female end on the pitch primary arm, make sure to keep the payload and the gimbal facing the front, while the microSD card slot points to the gimbal rear. Then use four M2 screws to install the payload onto the gimbal, with some thread glue applied on the screws to ensure secure installation.

2. Gently open the pitch secondary arm to put the secondary arm sleeve between the gimbal and payload. Apply an appropriate amount of 243 thread glue to the thread of the secondary arm mounting screw, tighten the screw from the other side of the secondary arm, and finally attach the secondary arm plug and ensure that it is pressed to the end.
3. Rotate the payload around the Pitch axis centerline and ensure that the payload can remain stationary at all positions.

4. Use an L-shaped hexagonal screwdriver to loosen the 4 screws on the Roll arm (no need to remove the screws), hold the yaw arm with one hand, and adjust the position of the roll arm to ensure that the roll arm can keep balance while rotating, then re-tighten the 4 screws.

5. Use an L-shaped hexagonal screwdriver to loosen the 4 screws on the yaw arm (no need to remove the screws), hold the yaw base with one hand, and adjust the position of the yaw arm to ensure that the gimbal can remain stationary (not rotate around the yaw base) at any position when the yaw base centerline is not perpendicular to the ground, then re-tighten the 4 screws.

6. Trim the yaw waterproof sticker to fit the gimbal, make sure there is about a 1 mm slot between the sticker and the gimbal, then remove the release paper to attach the waterproof sticker into the groove of the yaw arm.

7. Trim the roll waterproof sticker to fit the gimbal, and remove the release paper to attach the waterproof sticker into the groove of the roll arm.

⚠️ For the same payload, once adjustment is finished, you can record the adjustment position on the corresponding ruler on the yaw / roll arm. This reading can be referenced for each adjustment to save time in finding the center of mass position.
Mounting the X-Port Gimbal to the Aircraft

1. Align the white and red dots and insert the X-Port gimbal connector.
2. Rotate to lock the X-Port gimbal connector in place.

⚠️ Make sure to press down the gimbal detachment button when rotating the gimbal lock to remove the gimbal. The gimbal lock should be fully rotated when removing the gimbal for the next installation.

💡 The DJI Payload SDK Development Kit 2.0, purchased separately, can be used to debug the X-Port gimbal. Refer to the Payload SDK Development Kit 2.0 user guide for details.

Settings
Control parameter settings and user parameter settings can be done with DJI Assistant 2 For Matrice (hereinafter referred to as DA2) or DJI Pilot App.

The DA2 Page

Downloading and Installing the DA2 Software
Downloading and Installing the DA2 according to below link.
http://www.dji.com/matrice-200-series-v2/info#downloads

⚠️ Make sure to use the latest firmware for debugging.

Connecting to DA2
1. Make sure the gimbal is mounted to the aircraft correctly.
2. Connect the aircraft and the PC with a USB to USB cable.
3. Launch DA2 and log in with a DJI account. Click X-Port to access the settings.

Payload SDK Page Overview
Set the related parameters on the Payload SDK page.

The DJI Pilot App Page

Downloading and Installing the DJI Pilot App

Search for the DJI Pilot app in the Google Play Store to download and install the app on your mobile device. Make sure your mobile device is connected to the remote controller.

⚠️ Make sure to use the latest firmware for debugging.

Connecting to the DJI Pilot App

1. Make sure the gimbal is mounted to the aircraft correctly.
2. Make sure the remote controller and the aircraft is linked.
3. Launch DJI Pilot app and log in with a DJI account. Click Gimbal Settings to access the settings.

Gimbal Settings Page Overview

Set the related parameters on Gimbal Settings page.
Control Parameter Settings

⚠️ The following parameters cannot be adjusted by end users.

DO NOT use external modules to control the gimbal (including angle adjustment, speed adjustment and gimbal center).

The Gimbal Balance Test, Gimbal Coaxiality Test, Gimbal Parameter Auto-tuning, Gimbal Force Adjustment, and Reset Control Parameters are available on the Control Parameter Settings page of DA2 or the Gimbal Settings page of DJI Pilot app.

The following content uses the DA2 page as an example to describe setting operations.

Gimbal Balance Test

During Gimbal Balance Test, the three gimbal axis are in Joint Angle mode, and they can rotate at the same speed within the mechanical limits in sequence. If the gimbal is out of balance, the gimbal output will be changed under the influence of gravity during rotation, so that any imbalances and the direction of imbalances can be identified.

Here are the steps to the test:

1. Tap “Gimbal Balance Test” on “Gimbal Settings” page, and prepare the aircraft and gimbal according to app instructions.
2. Run the test according to app instructions.
3. Gimbal Balance Test needs to be rerun if the gimbal is found to be out of balance based on test progress and results. These adjustments maybe required:
   a. Move the payload forward (backward) and upward (downward) and perform the balance test again.
   b. Adjust the position of the gimbal Roll arm to the left (to the right) and perform the balance test again.
   c. Adjust the position of the gimbal Yaw arm forward (backward) and perform the balance test again.

Gimbal Coaxiality Test

During Gimbal Coaxiality Test, the gimbal pitch-axis is in Joint Angle mode, and it can rotate at the same speed within the mechanical limits. If the gimbal coaxiality is poor, the gimbal will not rotate smoothly at certain positions during rotation, hence the test identifies issues in gimbal coaxiality.

It is important to make sure the Gimbal Balance Test is finished and the gimbal is balanced before performing the Gimbal Coaxiality Test.

Here are the steps to the test:

1. Tap “Gimbal Coaxiality Test” on “Gimbal Settings” page, and prepare the aircraft and gimbal according to app instructions.
2. Run the test according to app instructions.
3. During Gimbal Coaxiality Test, you can adjust the mounting of the payload and the pitch secondary arm according to the coaxiality test progress and results. If the gimbal coaxiality is poor, please adjust the pitch secondary arm end screw hole forward or backward, upward or downward, and then perform the Gimbal Coaxiality Test again.

**Gimbal Parameter Auto-tuning**

Tap “Gimbal Parameter Auto-tuning” on “Gimbal Settings” page, then it will automatically adjust the gimbal control parameters according to the payload.

1. Mount the payload onto the gimbal, and make sure the Gimbal Balance Test and Gimbal Coaxiality Test are both ok.
2. Turn off the aircraft’s motors and keep the gimbal stationary (both roll and pitch angle are within ±5°), then the DA2 / DJI Pilot will start the Gimbal Parameter Auto-tuning.

**Gimbal Force Adjustment**

If the gimbal control force is too weak or too strong, you can adjust the force applied onto the gimbal using DA2 / DJI Pilot.

**Reset Control Parameters**

Performed to reset the control parameters.

---

**User Parameter Settings**

⚠️ The following parameters can be adjusted by end users.

The following parameters can be set on “User Parameter Settings” page of DA2 or “Gimbal Settings” of DJI Pilot app.

1. **The Start / Stop Buffer of Gimbal Pitch / Yaw**
   - The smaller the value (the greater the gimbal acceleration), the faster the gimbal responds when operating the remote controller dial, and the faster the gimbal can stop when the remote controller dial is released.
   - The greater the value (the smaller the gimbal acceleration), the slower the gimbal responds when operating the remote controller dial, and the slower the gimbal can stop when the remote controller dial is released.

2. **Gimbal Pitch / Roll / Yaw Adjust**
   - Once the gimbal is still not balanced after performing Gimbal Auto Calibration or when the manual adjustment is required, adjust these parameters.
Other Parameter Settings

The following parameters can be set on “Gimbal Settings” page in DJI Pilot app.

1. Gimbal Pitch Limit Extension
   The gimbal pitch control range is from -90° to +30° when turned off, and from -120° to +30° when turned on.

2. Max Gimbal Pitch / Yaw Speed
   The greater the value (the greater the gimbal speed), the faster the gimbal rotates when operating the remote controller dial.

Functions

⚠️ The following parameters can be adjusted by end users.

Gimbal Function Debugging

This function is available on “Gimbal Function Debugging” in DA2 or “Gimbal Settings” in DJI Pilot app.

1. Gimbal Pitch / Yaw Speed Adjustment
   Use the remote control dial or drag the Gimbal Pitch / Yaw Speed Adjustment slider on DA2 to control the gimbal rotating.

2. Gimbal Angle Adjustment
   Enter a pitch or yaw value in the Gimbal Angle Adjustment box to rotate the gimbal to a specific angle.

3. Gimbal Auto Calibration
   If the gimbal is still not balanced, tap Gimbal Auto Calibration to adjust it.

4. Re-centering the Gimbal
   Tap to center the gimbal.
Gimbal Control

Used the DJI Pilot app to control the gimbal.

1. Follow mode: Gimbal yaw will rotate with the aircraft yaw rotation.
   
   Free mode: Gimbal rotates freely.
   
   Reset: The gimbal pitch and roll will center.

2. Using the DJI Pilot app to control the gimbal
   
   Tap and slide on the app’s camera view to control the gimbal rotation.

Appendix

Specifications

<table>
<thead>
<tr>
<th>Compatible aircraft *</th>
<th>M200 series V2</th>
</tr>
</thead>
<tbody>
<tr>
<td>Weight</td>
<td>340 g</td>
</tr>
<tr>
<td>Dimensions</td>
<td>128×140×145 mm</td>
</tr>
<tr>
<td>Supported load weight range</td>
<td>&lt;450 g</td>
</tr>
</tbody>
</table>

Supported load dimensions:
The dimension of the load in the direction of the Pitch axis centerline is 80 mm. Draw a spherical surface with a diameter of 145 mm, using the mass center of the load as the center of the sphere. Ensure that the load locates at the back of the pitch axis centerline can be completely wrapped in the spherical surface when it moves.
<table>
<thead>
<tr>
<th>Item</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Gimbal angular vibration range **</td>
<td>±0.008°</td>
</tr>
<tr>
<td>Gimbal controllable range</td>
<td>Pitch: +30° to -120°, Yaw: ±320</td>
</tr>
<tr>
<td></td>
<td>If the load size is quite large, the gimbal controllable range may decrease. The actual controllable range is subject to the load.</td>
</tr>
<tr>
<td>Gimbal connector</td>
<td>DGC2.0</td>
</tr>
<tr>
<td>PSDK port power</td>
<td>13.6 V / 2A, 17V / 2.5 A</td>
</tr>
<tr>
<td>IP rating</td>
<td>IP44</td>
</tr>
<tr>
<td>Operating temperature</td>
<td>-20°C to 50°C (-4°F to 122°F)</td>
</tr>
</tbody>
</table>

* Please refer to the DJI official website for more information about the latest compatible aircraft types.
** Measured when hovering in windless conditions, which may be affected by the aircraft’s flight status, wind speed, and load inertia.

### Firmware and Software Version Requirements

<table>
<thead>
<tr>
<th>Device</th>
<th>Version</th>
</tr>
</thead>
<tbody>
<tr>
<td>M200 series V2 aircraft firmware</td>
<td>V01.00.0650</td>
</tr>
<tr>
<td>GL900A remote controller firmware</td>
<td>V01.00.0650</td>
</tr>
<tr>
<td>Pilot APP</td>
<td>V1.7.0</td>
</tr>
<tr>
<td>MSDK</td>
<td>V4.12</td>
</tr>
<tr>
<td>DJI Assistant2 for Matrice win</td>
<td>V02.00.11</td>
</tr>
<tr>
<td>DJI Assistant2 for Matrice mac</td>
<td>V02.00.11</td>
</tr>
</tbody>
</table>

### Firmware Update

Mount the gimbal onto the aircraft, connect the aircraft to the PC with a USB cable. Launch DA2 and select X-Port, then go to the firmware update page.
Log Export

1. Gimbal log export
   A micropSD card with a capacity of up to 32G can be inserted into the card slot on the gimbal to store the gimbal logs. If the gimbal fails, you can connect the microSD card to your computer, and copy the files in DAT format at the corresponding time and provide it to DJI support for analysis.

2. PSDK log export
   PSDK logs are stored on the aircraft. If there is a problem with the PSDK, you can connect the aircraft to your computer, use the DA2 log export function to export flight data, and provide it to DJI support for analysis.

Mounting the Extended Landing Gears

If you use the M200 series V2 aircraft, the extended landing gears (excluded) are required since the gimbal may touch the ground during self-test.

Using the Special Gimbal Dampers

If you use the M200 series V2 aircraft, the special gimbal dampers (excluded) are required when attaching the X-Port gimbal onto the aircraft.

Obstruction in Dual Gimbal Installation

During dual gimbal usage, X-Port gimbal may obstruct another gimbal when they are both rotating.

The X-Port centroid has a variable position, and the scenario described below is using the longest yaw arm and does not consider the size of the front end of the load.

The obstruction angles during rotation of different gimbals are shown in the below table, where the obstruction angle 1 is the angle range when the gimbal is rotating clockwise, and the obstructing angle 2 is the angle range when the gimbal is rotating counterclockwise.

The details of using the M200 Series V2 aircraft are shown in the figure below. The X-Port gimbal is installed in gimbal position B, and another gimbal is installed in gimbal position A. The angle at which both gimbals face forward is the zero point and the counterclockwise is positive.
Below table shows the obstruction angle during the rotation when using dual gimbals.

<table>
<thead>
<tr>
<th>NO.</th>
<th>Gimbal position</th>
<th>Gimbal type</th>
<th>Obstruction angle 1</th>
<th>Obstruction angle 2</th>
<th>Dual gimbal obstruction range</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>A</td>
<td>Zenmuse XT</td>
<td>-256.15° ~-283.85°</td>
<td>+76.15° ~+103.85°</td>
<td>27.70°</td>
</tr>
<tr>
<td></td>
<td>B</td>
<td>X-Port</td>
<td>-82.34° ~-97.67°</td>
<td>+262.33° ~+277.66°</td>
<td>15.33°</td>
</tr>
<tr>
<td>2</td>
<td>A</td>
<td>Zenmuse Z30</td>
<td>-235.75° ~-304.25°</td>
<td>+55.75° ~+124.25°</td>
<td>68.50°</td>
</tr>
<tr>
<td></td>
<td>B</td>
<td>X-Port</td>
<td>-64.69° ~-115.31°</td>
<td>+244.69° ~+295.31°</td>
<td>50.62°</td>
</tr>
<tr>
<td>3</td>
<td>A</td>
<td>Zenmuse X5S</td>
<td>-237.40° ~-302.60°</td>
<td>+57.40° ~+122.60°</td>
<td>65.20°</td>
</tr>
<tr>
<td></td>
<td>B</td>
<td>X-Port</td>
<td>-66.97° ~-113.03°</td>
<td>+246.97° ~+293.03°</td>
<td>46.06°</td>
</tr>
<tr>
<td>4</td>
<td>A</td>
<td>Zenmuse XT2</td>
<td>-242.93° ~-297.07°</td>
<td>+62.93° ~+117.07°</td>
<td>54.14°</td>
</tr>
<tr>
<td></td>
<td>B</td>
<td>X-Port</td>
<td>-72.87° ~-107.13°</td>
<td>+252.87° ~+287.13°</td>
<td>34.26°</td>
</tr>
<tr>
<td>5</td>
<td>A</td>
<td>X-Port</td>
<td>-229.99° ~-310.01°</td>
<td>+49.99° ~+130.01°</td>
<td>80.02°</td>
</tr>
<tr>
<td></td>
<td>X-Port</td>
<td>X-Port</td>
<td>-49.99° ~-130.01°</td>
<td>+229.99° ~+310.01°</td>
<td>80.02°</td>
</tr>
</tbody>
</table>

As shown in the table above, when an M200 Series V2 aircraft is mounted with two X-Port gimbals, the obstruction angle is 80.02 °. Note that the above data are theoretical values, without considering the vibration, wind direction, the aircraft tilt and the aircraft braking during actual flight, and are for reference only. In addition, the actual attitude of gimbal A could affect the rotation range of gimbal B.

⚠️ When the front end of the payload exceeds a certain size, the obstruction will be the payload itself rather than the gimbal body.
Compliance

FCC Compliance

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) This device must accept any interference received, including interference that may cause undesired operation.

Supplier’s Declaration of Conformity

Product name: DJI ENTERPRISE X-PORT
Model Number: PSDK-XP01
Manufacturer’s Name: SZ DJI TECHNOLOGY CO., LTD.
Manufacturer’s Address: 14th floor, West Wing, Skyworth Semiconductor Design Building No.18 Gaixian South 4th Ave, Nanshan, Shenzhen, Guangdong, China
Responsible Party: DJI Technology, Inc.
Responsible Party Address: 201 S. Victory Blvd., Burbank, CA 91502

Contact person: Fajia Wang
Telephone: (650)812-0559

We, DJI Technology, Inc., being the responsible party, declares that the above mentioned model was tested to demonstrate complying with all applicable FCC rules and regulations. This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Signed for and on behalf of: DJI Technology, Inc.
Name: Fajia Wang
Position: Certification Manager
Date: 2020-03-20
Signature: 

ISED Compliance

CAN ICES-3 (B)/NMB-3(B)

EU Compliance Statement: SZ DJI TECHNOLOGY CO., LTD. hereby declares that this device is in compliance with the essential requirements and other relevant provisions of the Directive 2014/30/EU.

A copy of the EU Declaration of Conformity is available online at www.dji.com/eu-compliance.

EU contact address: DJI GmbH, Industriestrasse 12, 97618, Niederlauer, Germany

Declaración de cumplimiento UE: SZ DJI TECHNOLOGY CO., LTD. por la presente declara que este dispositivo cumple los requisitos básicos y el resto de provisiones relevantes de la Directiva 2014/30/EU.

Hay disponible online una copia de la Declaración de conformidad UE en www.dji.com/eu-compliance.

Dirección de contacto de la UE: DJI GmbH, Industriestrasse 12, 97618, Niederlauer, Germany

EU-Verklaring van overeenstemming: SZ DJI TECHNOLOGY CO., LTD. verklaart hierbij dat dit apparaat voldoet aan de essentiële vereisten en andere relevante bepalingen van Directive 2014/30/EU.

Het is beschikbaar online een kopie van de EU-conformiteitsverklaring op www.dji.com/eu-compliance.

Kontaktpartij adres: DJI GmbH, Industriestrasse 12, 97618, Niederlauer, Germany

EU declaration of conformity: SZ DJI TECHNOLOGY CO., LTD. hereby declares that this device is in conformity with the essential requirements and other relevant provisions of Directive 2014/30/EU.

EU Declaration of Conformity is available online at www.dji.com/eu-compliance.

EU contact address: DJI GmbH, Industriestrasse 12, 97618, Niederlauer, Germany

Dichiarazione di conformità UE: SZ DJI TECHNOLOGY CO., LTD. dichiara attualmente in base alla direttiva 2014/30/UE.

Esiste una copia della Dichiarazione di conformità UE disponibile on line www.dji.com/eu-compliance.

Endereço de contacto na UE: DJI GmbH, Industriestrasse 12, 97618, Niederlauer, Germany

EU declaration of conformity: SZ DJI TECHNOLOGY CO., LTD. declares that this device is in conformity with the essential requirements and other relevant provisions of Directive 2014/30/EU.

A declaration of compliance is available online at www.dji.com/eu-compliance.

EU contact address: DJI GmbH, Industriestrasse 12, 97618, Niederlauer, Germany

Deklaracija o shodnosti EU: Spoljna kompanija „DSJ Technology Co., Ltd.” tijekom ovog postupka izjavljuje da je ova uređaja u shodnosti s direktivama 2014/30/UE.

EU Declaration of Conformity is available online at www.dji.com/eu-compliance.

EU contact address: DJI GmbH, Industriestrasse 12, 97618, Niederlauer, Germany

Deklaracija za sukladnost EU: SZ DJI Technology Co., Ltd. deklarira, da je v tej vrsti naprave izvedba v skladu z osnovnimi postaneki in drugimi relevantnimi pravilniki Direktive 2014/30/EU.

EU Declaration of Conformity is available online at www.dji.com/eu-compliance.

EU contact address: DJI GmbH, Industriestrasse 12, 97618, Niederlauer, Germany

Извънска оценка за съответствие ЕС: SZ DJI Technology Co., Ltd. декларира, че това устройство отговаря на основните изисквания и другите приложими разпоредби на Директива 2014/30/ЕС.

Copie prohlášení o shodě pro EU je k dispozici on-line na webu www.dji.com/eu-compliance.

EU declaration of conformity: SZ DJI Technology Co., Ltd. hereby declares that this device is in conformity with the essential requirements and other relevant provisions of Directive 2014/30/EU.

EU contact address: DJI GmbH, Industriestrasse 12, 97618, Niederlauer, Germany

Akkoord van overeenkomst: SZ DJI Technology Co., Ltd. verklaart hierbij dat dit apparaat voldoet aan de essentiële vereisten en andere relevante bepalingen van Richtlijn 2014/30/UE.

De klant kan een kopie van de EU-overeenstemmingsverklaring online vinden op de website www.dji.com/eu-compliance.

EU contact address: DJI GmbH, Industriestrasse 12, 97618, Niederlauer, Germany

Разрешительное заявление: SZ DJI Technology Co., Ltd. заявляет о соответствии устройства основным требованиям и другим применимым положениям Директивы 2014/30/UE.

EU Declaration of Conformity is available online at www.dji.com/eu-compliance.

EU contact address: DJI GmbH, Industriestrasse 12, 97618, Niederlauer, Germany

Deklaracija o shodnosti EU: Spoljna kompanija „DSJ Technology Co., Ltd.” tijekom ovog postupka izjavljuje da je ova uređaja u shodnosti s direktivama 2014/30/UE.

EU Declaration of Conformity is available online at www.dji.com/eu-compliance.

EU contact address: DJI GmbH, Industriestrasse 12, 97618, Niederlauer, Germany

Deklaracyjny zgodności UE: SZ DJI Technology Co., Ltd. deklaruje, że urządzenie jest zgodne z podstawowymi wymogami oraz innymi stosownymi postanowieniami dyrektywy 2014/30/UE.

Copies prohlášení o shodě pro EU je k dispozici on-line na webu www.dji.com/eu-compliance.

EU declaration of conformity: SZ DJI Technology Co., Ltd. hereby declares that this device is in conformity with the essential requirements and other relevant provisions of Directive 2014/30/EU.

EU contact address: DJI GmbH, Industriestrasse 12, 97618, Niederlauer, Germany

Deklaracija o shodnosti EU: Spoljna kompanija „DSJ Technology Co., Ltd.” tijekom ovog postupka izjavljuje da je ova uređaja u shodnosti s direktivama 2014/30/UE.

EU Declaration of Conformity is available online at www.dji.com/eu-compliance.

EU contact address: DJI GmbH, Industriestrasse 12, 97618, Niederlauer, Germany

Deklaracja o zgodności UE: Firma SZ DJI Technology Co., Ltd. niniejszym stwierdza, że przedstawione urządzenia jest zgodne z zasadniczymi wymaganiami i innymi stosownymi postanowieniami dyrektywy 2014/30/UE.

Copies prohlášení o shodě pro EU je k dispozici on-line na webu www.dji.com/eu-compliance.

EU declaration of conformity: SZ DJI Technology Co., Ltd. hereby declares that this device is in conformity with the essential requirements and other relevant provisions of Directive 2014/30/EU.

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EU contact address: DJI GmbH, Industriestrasse 12, 97618, Niederlauer, Germany

Deklaracyjny zgodności UE: SZ DJI Technology Co., Ltd. deklaruje, że urządzenie jest zgodne z podstawowymi wymogami oraz innymi stosownymi postanowieniami dyrektywy 2014/30/UE.
Environmentally friendly disposal

Old electrical appliances must not be disposed of together with the residual waste, but have to be disposed of separately. The disposal at the communal collecting point via private persons is for free. The owner of old appliances is responsible to bring the appliances to these collecting points or to similar collecting points. With this little personal effort, you contribute to recycle valuable raw materials and the treatment of toxic substances.

Milieuvriendelijk afvoeren

Elektrische apparaten die op de oude computer vallen, mogen niet samen met de restafval worden afgevoerd. Het eigenaar van deze houdt zich er echter dan verantwoordelijk voor om de apparaten te laten afvoeren via de gemeentelijke verzamelpunt voor particulieren of een vergelijkbaar punt. Met deze kleine persoonlijke inspanning lever je een bijdrage aan het recyclen van waardevolle grondstoffen en de verwaring van giftige stoffen.

Eliminazione ecologica

Gli apparecchi elettrici antichi non possono essere eliminati insieme ai rifiuti residui, ma devono essere smaltiti separatamente. La smaltimento da parte di soggetti privati deve essere gratuito. L'impresario dei prodotti elettronici deve essere responsabile per il trasporto dei prodotti di elettronica a questo punto di raccolta a punti di raccolta analoghi. Grazie a questo piccolo impegno, il contributo alla riciclaggio dei materiali e alla corretta gestione delle sostanze tossici.

Smaltimento ecologico

I vecchi dispositivi elettrici non devono essere smaltiti insieme ai rifiuti residui, ma devono essere smaltiti separatamente. Lo smaltimento da parte di soggetti privati è gratuito. Il proprietario del dispositivo elettronico deve essere responsabile per il trasporto dei dispositivi elettronici a punti di raccolta di punti di raccolta analoghi. Grazie a questo piccolo impegno, il contributo alla riciclaggio dei materiali e primi usi e alla otramento di sostanze tossiche.

Eliminación ecológica

Aparatos eléctricos usados no pueden ser eliminados juntos con los residuos, deben ser eliminados separadamente. La eliminación a cargo de particulares y puntos de recogida público, es gratuito. Se responsabiliza el propietario de los aparatos electrónicos para que sean deportados a los puntos de recogida y similares a ellos. Con este pequeño esfuerzo, contribuye a la reciclaje de materiales valiosos y al tratamiento de sustancias tóxicas.

Abfälle ordnungsgemäß unschädlich machen

Older electronic appliances must not be disposed of with the residual waste, but must be disposed of separately. The community collection point via private persons is for free. The owner of the older appliances is responsible for bringing the appliances to these collection points or similar collection points. With this little personal effort, you contribute to recycling valuable raw materials and the treatment of toxic substances.

Utylizacja przyjazna dla środowiska

Stare elektryczne urządzenia nie mogą być utylizowane razem z odpadami normalnymi. Właściciel jest odpowiedzialny za przekazanie urządzeń do punktu wojewódzkiego lub tzw. punktu publicznego. Dzięki temu małemu wysiłkowi, możesz przyczynić się do recyklingu wartościowych surowców i obróbki toksycznych substancji.

Környezetbarát hulladékkezelés

Elektrinių prietaisų savininkai utilizuojamus prietaisus privalo priduoti į atitinkamus arba tais samgesčius kasybos punktus. Per šią mažą iniciatyvą, ataka gali prisidedi prie laimės drąsos ir apsaugos naikinimui.
## DJI ENTERPRISE X-PORT User Manual

## 有害物质含量

<table>
<thead>
<tr>
<th>部件名称</th>
<th>铅（Pb）</th>
<th>汞（Hg）</th>
<th>镉（Cd）</th>
<th>六价铬（Cr⁶⁺）</th>
<th>多溴联苯（PBB）</th>
<th>多溴二苯醚（PBDE）</th>
</tr>
</thead>
<tbody>
<tr>
<td>线路板</td>
<td>×</td>
<td>○</td>
<td>○</td>
<td>○</td>
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<td>○</td>
</tr>
<tr>
<td>外壳</td>
<td>×</td>
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<tr>
<td>金属部件（铜合金）</td>
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</tr>
<tr>
<td>内部线材</td>
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<tr>
<td>其他配件</td>
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<td>○</td>
</tr>
</tbody>
</table>

本表格依据 SJ/T 11364 的相关规定。

- Ｘ：表示该有害物质在该部件的所有均质材料中的含量均在 GB/T 26572 规定的限量要求以下。
- ○：表示该有害物质至少在该部件的某一均质材料中的含量超出 GB/T 26572 规定的限量要求。 (产品符合欧盟 ROHS 指令环保要求)