# Scratch 3.0 Tello Extension

v1.1 20211013

#### **Overview**

Tello Extension allows users to use Scratch 3.0 to control Tello with visual programming.

# **Safety Features**

After Tello executes the current command, if there is no additional command input after 15 seconds, the drone will automatically land.

#### Reset the Wi-Fi

The extension only supports Direct Wi-Fi (AP mode). If Tello enters STA mode, you can press and hold the power button for 5s when the drone is on. The status indicator will turn off and the drone will restart. When the status indicator blinks yellow, the Wi-Fi SSID will restore to factory settings, with no set password by default.

### **Architecture**

Build Wi-Fi communication between Tello and computer.

Tello IP: 192.168.10.1 UDP PORT: 8889 << - - >> computer

The extension will automatically create two UDP clients that bind to '0.0.0.0:45689' and '0.0.0.0:8890' respectively. Port '45678' is responsible for sending and receiving commands to Tello. Port '8890' is responsible for receiving Tello status information. Before using the extension, make sure both ports are available.

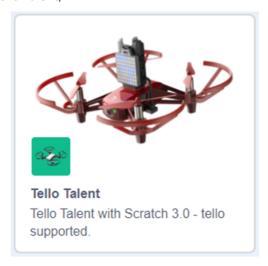
# **Quick Start**

1. Power on Tello, connect computer to Tello's Wi-Fi, and launch Scratch 3.0 for Tello Extension;

2. Click the *Add Extension* button on the bottom left corner to open the extension selection interface;



3. Click the extension Tello Talent;



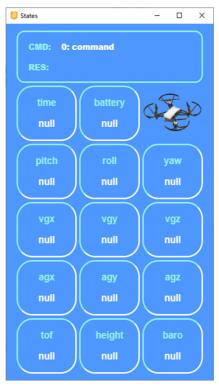
4. Read the command block instructions, and drag the blocks to use them. You can see one example bellow. A *connect* block is always required at the beginning of the program. A *wait execute all cmds* block is required at the end of any non-blocking command (blocking and non-blocking commands will be explained later);



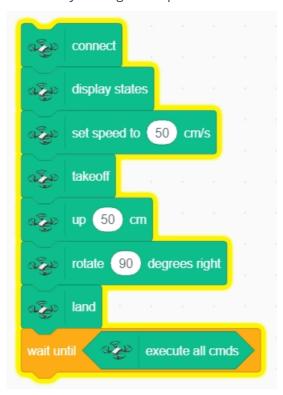
5. Click the code block to initiate the program. A *Connecting* window will pop up to connect with Tello. Once the drone is connected, the *Connecting* window will close automatically and the programs will run successively. The *connect* block will execute the connection command before running every code to make sure Tello is stably connected to the computer;



6. As a state display block is used, the Tello status window will appear and can be closed at any time;



7. While a program is running, the entire code module will be highlighted in yellow. You can stop the program mid-execution by clicking the *Stop* button.



# **Blocking and Non-blocking**

Besides blocking modes in plain-text send blocking ▼ command command , all

other blocks are non-blocking.

#### Non-blocking Blocks

When using non-blocking blocks, all command blocks will automatically be set to completed and then send a *land* command to end the program. After that, the entire code module will no longer be highlighted in yellow and the *Stop* button will not be functional.

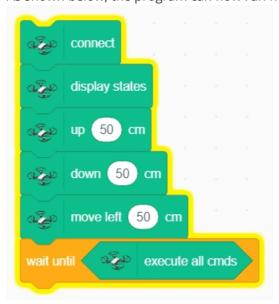
As shown in the illustration, the program will directly complete and exit.



To turn an unblocking block into a blocking state, put wait execute all cmds



As shown below, the program can now run normally.



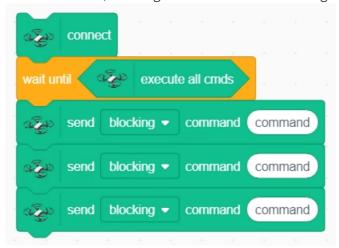
#### **Blocking Blocks**

Blocking blocks can be used independently without the wait executive all cmds block



successively, which means a command will only execute when the previous one is completed.

As shown below, blocking blocks can enter a blocking state.



#### **Combination of Blocking and Non-blocking Blocks**

As shown below, all non-blocking blocks should end with



and then be followed by blocking blocks. There are no limits for connections between blocking blocks. A blocking block can be followed directly by a non-blocking one.

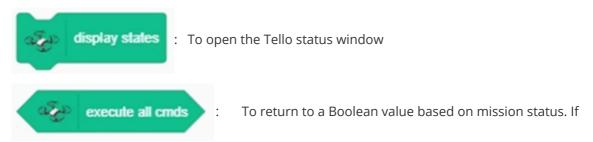


# **Command Blocks**



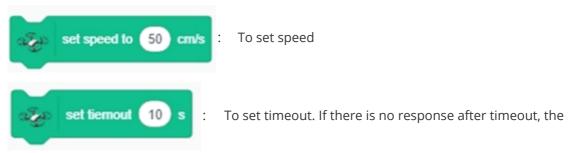
Tello before adding more blocks

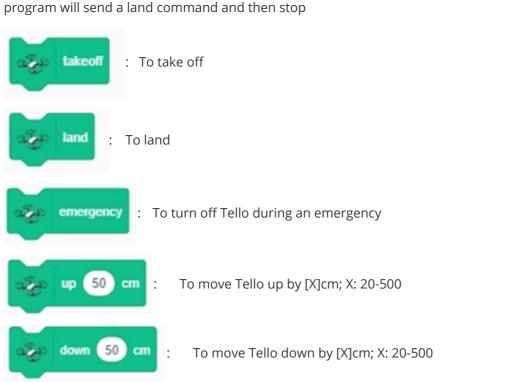
**Note:** This block must be put at the beginning of the Tello program.

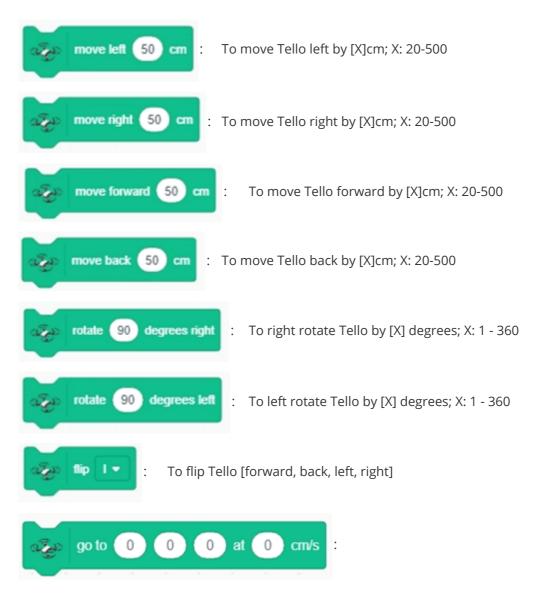


the mission is completed, return to true; if not, return to false







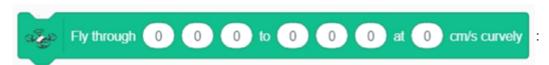


To set the speed at (cm/s) and fly to (x,y,z);

x: -500 - 500 y: -500 - 500 z: -500 - 500

speed: 10-100 (cm/s);

x, y and z should not be in the -20 to 20 range all at the same time.



To set the speed at (cm/s) and fly through (x1,y1,z1) in a curve to (x2,y2,z2). If the curve radius is not in the 0.5-10 meters range, return relevant notifications;

x1, x2: -500 - 500 y1, y2: -500 - 500

z1, z2: -500 - 500 speed: 10-60 (cm/s)

x, y and z should not be in the -20 to 20 range all at the same time.



Plain-text command: To send plain-text commands in non-blocking or blocking mode.

To learn more about plain-text command, please refer to <u>Tello SDK 3.0 User Guide</u>.

# **Status Information**



CMD: Command number: current command

RES: Command number: return information of the command

time: flight time after Tello takes off

battery: remaining power of Tello

pitch: pitch angle

roll: roll angle

yaw: yaw angle

vgx/vgy/vgz: speed on x,y,z

agx/agy/agz: acceleration on x,y,z

tof: height from the ground

height: height from the takeoff point

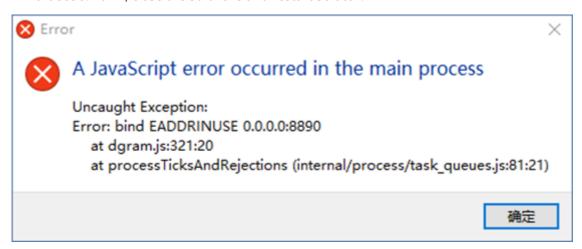
baro: height of the barometer

# **FAQs**

1. Command Block Compatibility with Tello and Tello Talent.

Only established blocks in the extension supports Tello. Other plain-text commands in SDK 3.0 do not support Tello. Using unsupported commands will lead to an *Unknown Command* notification in the *RES* status window.

2. If the following error occurs when launching Scratch, it means another software is occupying Port 8890. To fix, close the software and restart Scratch.



#### Detailed steps:

(1) Press **win+R** to launch Command Input and enter **powershell** to open up the Windows Terminal;



(2) Enter *netstat -aon* | *findstr "8890"* in the Terminal to get the program pid;



(3) Enter *taskkill /T /F /PID 16908* in the Terminal (16908 is the pid value returned in the last step), close the program and restart Scratch.